



**The
(yet-in)
complete
guide
to
Soya 3D**

(also known as “the yet-in”)

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Chapter 1

Introduction

1.1 License

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1.2 What is Soya 3D ?

1.3 History

The actual Soya was originally written by Jiba and Blam. Jiba is the man that has written seven 3D engines:

1. a 3D engine ("Vertige 3D") in visual basic + direct X
2. a 3D engine in visual basic + OpenGL (direct X was too horrible)
3. a second 3D engine in visual basic + OpenGL (rewrite of the previous one)
4. a 3D engine ("Opale.Soya") in Java + OpenGL (my last engine was too big to compile with VB!)
5. a 3D engine ("Opale.Soya 2") in Java + OpenGL (rewrite of the previous one, with my brother Blam)
6. a 3D engine ("Soya" < 0.7) in Python + C + OpenGL (Python was now more appealing for me than Java, still helped by Blam for the C part)
7. a 3D engine ("Soya" >= 0.7) in Python + Pyrex + OpenGL (I was not at ease with C and Blam was gone)

The engine in visual basic have never been published (I haven't got the Internet at this time!). The Java engine have been published and can still be found on the web; in particular they were used in Arkanae. They are no longer maintained.

Then, after trying an aggressive take-over on Soya, Arc Riley has forked the project into PySoy, on June the 6th in 2006. Arc still own the soya3d.org domain name, and use it as a placeholder spreading false and slanderous allegations.

Arc was considering me (=Jiba) as a "bad leader" for the project. After having written the Soya 3D engine and several games (including Arkanae, Slune, Balazar and Balazar Brothers), I consider that I am definitely a great leader and that the technical directions I have chosen are right. I don't claim being a good manager, though ;-)

You can find more historical information on <http://home.gna.org/oomadness/en/soya/history.html>.

1.4 The Soya project objectives and the Soya spirit

Here are the spirit that Soya follows (or *should* follow ;-):

- **Soya's goal #1 is to allow to develop as rapidly as possible** 3D games and other 3D apps
(Rationale: Soya targets "amateur" developpers, who code during their limited free time! Moreover, rapid development allows to gain a precious time that can be re-invested in improving your code or testing your app. For game, it leads to a better gameplay)
- **Soya's goal #2 is to be as easy as possible to learn**, in particular for people with no 3D background at all
(Rationale: Soya is not a toy; to be easy to learn is only goal #2 since any newbie will, a day, not longer be a newbie)

- **Despite its simplicity, Soya never sacrifices performance and speed**
(Rationale: speed is important for 3D game!)
- **Soya's API does not necessarily fit to the mathematical, computational or technical reality of the 3D**, e.g. Soya API does not require the use of matrices
(Rationale: math are not the natural way to represent 3D object. Soya should be useable without an important mathematical background. However, Soya provides matrices, mainly for debug purpose)
- **Soya relies a lot on Python facilities and modules**, e.g. saving 3D model is done through object serialization. As a consequence, Soya won't evolve toward a multi-language 3D engine and will stay Python-centred
(Rationale: Python modules ease the Soya development, but also the use of Soya, since they are already well-known to Python developers)
- **Soya has plenty of dependencies**
(Rationale: any good OS has a package system tools today)
- **Soya always assumes by default the most common usecase**
(Rationale: doing so lead to a substencial time gain)
- **Soya is an "atypic" 3D engine and relies on a certain number of controversial choices** that are somehow debatable ; however, most of these choices are deliberate
(Rationale: Soya should be seen as a "research project" aiming at "a new way for 3D" ; the objective is not to satisfy anyone, but to be the ideal 3D engine for a few persons. Python does similarly)

1.5 Documentation available

1.5.1 Docstrings

About half of Soya objects and functions have docstrings. You can use pydoc to read them, or just type *e.g.* "help(soya.Body)" in a Python interpreter. You can also browse the doc online at <http://home.gna.org/oomadness/en/soya/pydoc.html>.

1.5.2 Tutorials

The Soya tutorial pack includes many tutorials, demos and examples.

1.5.3 About this doc

The (yet-in)complete guide to Soya 3D, also known as "the yet-in", is still under writing.

1.6 Getting help

You may ask for help either on the Soya's mailing list (soya-user@gn.org, suscribe from <http://mail.gna.org/listinfo/soya-user>) or the #soya IRC channel on FreeNode. Please check if you cannot find the reply to your question in the documentation listed above, though.

Chapter 2

Soya's basics

2.1 Initializing Soya

Initializing Soya is done in three steps, corresponding to these three lines:

```
import soya
soya.path.append("/your/data/path")
soya.init("My 3D app", sound = 1)
```

1. Importing module. Soya has several Python sub-packages, but most of the basic stuff is directly in the soya module.
2. Setting data path. The data directory (`/your/data/path` above) is referred as `<data>/` in this documentation; it is expected to contain several subdirectories (see section 3).

Hint: if your data are in the “data” directory located in the same directory than your script, a common trick for Python script is:

```
soya.path.append(os.path.join(os.path.dirname(sys.argv[0]), "data"))
```

and for Python module:

```
soya.path.append(os.path.basename(__file__), "data"))
```

3. Creating and showing the 3D display. `soya.init` can take the following arguments (all being optional):

title is the title of the window (windowed mode only, defaults to “Soya 3D”).

width, height the dimensions of the 3D screen (default to 640, 480).

fullscreen is true for fullscreen and false for windowed mode (defaults to false).

resizeable is true for a resizeable window (windowed mode only, defaults to true).

create_surface is true for creating an OpenGL surface through SDL, and false for using whatever OpenGL that is currently active (in this case it is up to you to initialize OpenGL, *e.g.* with PyGame, see section 13.2; it defaults to true)

sound is true to initialize 3D sound support (default to false for backward compatibility). There are other sound-related arguments, which are discussed in section 7.3.

You can use `soya.set_video(width, height, fullscreen, resizable)` to change some of these parameters after initialization.

The rest of this documentation assume that you have initialized Soya correctly. It may also assume that you have imported some common modules (`os`, `sys`,...), well, you are probably enough intelligent to understand that ;-).

2.2 Basic classes

The UML schema of figure 2.1 shows Soya's basic classes:

MainLoop is in charge of managing and regulating time (see section 2.7).

CoordSyst is the base class for all 3D objects. It defines a coordinate system, *i.e.* it has a 3D position, orientation and size.

Light is a light.

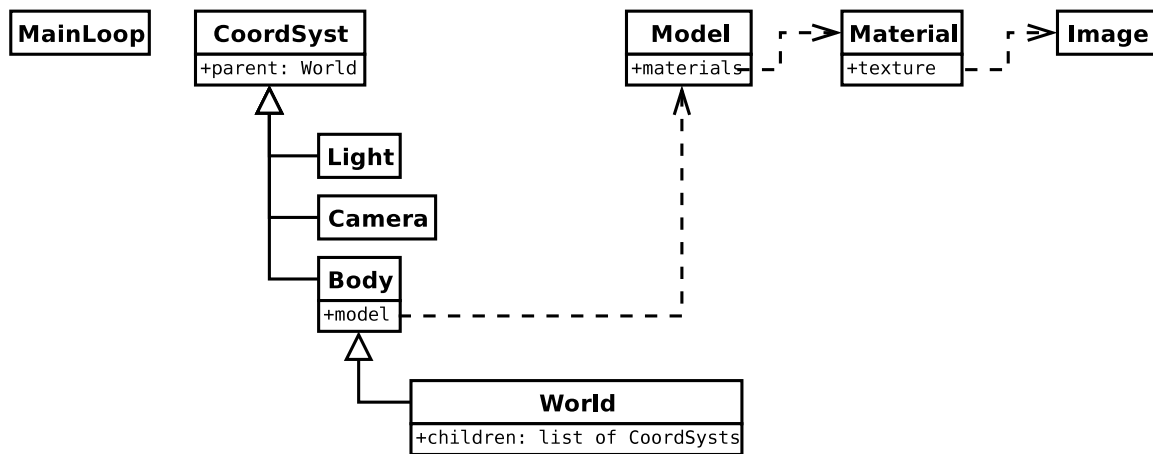


Figure 2.1: Soya’s basic classes (UML schema)

Camera is the “eye” from which the 3D scene is viewed. It also acts as the “ear”, for 3D sound.

Model (sometimes called “Mesh” in other 3D engines) is a 3D model. Model is actually an “abstract” class, and Soya provides several Model subclasses (SimpleModel, AnimatedModel,...). Models are created either by exporting them from 3D modelers (see chapter 5) or by creating a World, putting Faces in the World and then “compiling” the World into a Model (see chapter 10).

Material defines the attributes of a surface, *e.g.* color or texture.

Image is a 2D image. It is used in particular for textures. Images are usually created using a 2D painting program like The Gimp.

Body (sometimes called “Entity” in other 3D engines, or “Object” in Blender) displays a Model at a specific 3D position. Model cannot be displayed without “emBodying” them; it allows to display the same Model at several location (*e.g.* two identical houses in a town), by creating two Bodies with the same Model.

World (sometimes called “Node” or “Group” in other 3D engines) acts as a grouping container. A World can contain other nested CoordSysts, including other Worlds. When a World is moved, all the CoordSysts it contains are moved too. As a consequence, Soya scenegraph is a tree structure, the root being a World, usually called “scene”. World also inherit from Body, and thus can display a Model.

Most of the more advanced Soya classes derive from these.

Hint: some people find odd that World inherits from Body... but this will make sense in section 4.5, please wait ;-)

History: For a long time, Soya has used “folkloric” names. These names are still available as aliases, for backward compatibility (and archeologists :-). They are: Idler for MainLoop, Shape for Model, Volume for Body, Land for Terrain (see section 9.1).

2.3 Your first 3D scene with Soya

We are going to create a basic 3D scene that just displays a Model. First, we need to create the root of the tree, a World we call “scene” (Worlds with no parent are usually called “scene”). Then we load the Model and create a Body that displays it. Then we create a Light and a Camera, and we set the Camera as the *root widget*, *i.e.* the object Soya renders (see chapter 11). Finally, we create the MainLoop and start looping. The scene tree is the following:

```

World scene
|
+--- Body sword, displaying the sword Model
|
+--- Light light
|
+--- Camera camera
  
```

And here is the code (see tutorial basic-1.py):


```

scene = soya.World()

sword_model = soya.Model.get("sword")

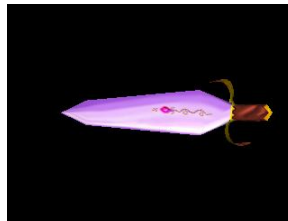
sword = soya.Body(scene, sword_model)
sword.x = 1.0
sword.rotate_y(90.0)

light = soya.Light(scene)
light.set_xyz(0.5, 0.0, 2.0)

camera = soya.Camera(scene)
camera.z = 2.0

soya.set_root_widget(camera)
soya.MainLoop(scene).main_loop()

```



In the next sections, we are going to see in more details the various objects used in this first example.

2.4 Loading Images, Materials and Models

Models are usually not created but loaded from a file (if you want to create Models directly from Soya, see chapter 10). To load a Model, do:

```
your_model = soya.Model.get("your_model_filename")
```

and Soya loads the `<data>/models/your_model_filename.data` file. The Materials and Images used by the Model are also automatically loaded, from the `<data>/materials/` and `<data>/images/` directories. Image files are PNG or JPEG, and Material and Model files are raw serialized Python objects, a format that only Soya can read or write.

However, Soya can import Blender models automatically. If a `<data>/blender/your_model_filename.blend` file exist, and the Model file doesn't exist (or is older), Soya loads the Blender files and caches the resulting Model in `<data>/models/your_model_filename.data`. This feature is known as "auto-exporters"; for more details on auto-exporters or data management, see chapter 3, and for more details on using Blender with Soya, see chapter 5.

If you call `Model.get` several times with the same filename argument, Soya doesn't load the Model twice but returns the same (cached) object. This is nice since Models are immutable.

2.5 Displaying Models with Bodies

Models cannot be directly displayed on the screen; you need to put them onto a Body. You can create a Body as following:

```
your_body = soya.Body(parent, model)
```

where `parent` is the World in which the Body is added, and `model` is the Model to display (both default to `None`). For all constructors of 3D objects (derivating from `CoordSyst`), the first argument is the parent World. It is possible to reparent a `CoordSyst`, and the current parent World can be accessed through the `parent` attribute.

The Model displayed by a Body can be get or set through the `model` attribute:

```
your_body.model = soya.Model.get("your_second_model_filename")
```

Bodies allow to display several times the same Model. For example, to display two swords instead of one, you can use the following scene tree:

```

World scene
|
+-- Body sword1, displaying the sword Model
|

```

```

+--- Body sword2, displaying the sword Model
|
+--- Light light
|
+--- Camera camera

```

And here is the code (`set_xyz` and `rotate_y` are used to position the two Bodies and will be seen in the next section; the code snippet doesn't include the scene, Light, Camera and MainLoop, which are identical to the "first scene" example):

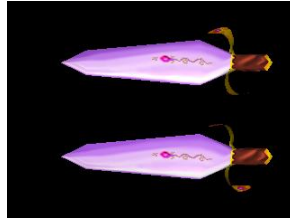
```

sword_model = soya.Model.get("sword")

sword1 = soya.Body(scene, sword_model)
sword1.set_xyz(1.0, 0.5, 0.0)
sword1.rotate_y(90.0)

sword2 = soya.Body(scene, sword_model)
sword2.set_xyz(1.0, -0.5, 0.0)
sword2.rotate_y(90.0)

```



2.6 Moving, rotating and scaling CoordSysts

Moving, rotating and scaling methods belong to the `CoordSyst` class, and are inherited to all `CoordSyst` children classes. This section shows the most common Moving, rotating and scaling methods; for a complete reference see section 2.13.3.

2.6.1 Soya's conventions

- When relevant, Soya always considers X as the right-hand direction, Y as the up direction, Z as the backward direction, and thus -Z as the frontward direction (Soya uses -Z for front in order to keep all coordinate systems right-handed, just to avoid an internal mathematical nightmare).
- All angles are expressed in degrees.
- In Soya, a 3D position is defined by three X, Y, Z values **and** the `CoordSyst` in which they are expressed. X, Y, Z alone are not enough to make a 3D position.
- By default, a distance of 1.0 is considered as roughly one meter, although you may choose a different convention.

2.6.2 Moving

The most basic method for moving an object is to set his x, y or z attributes. `set_xyz` sets x, y and z in a single call.

```

coord_syst.x = 1.0
coord_syst.set_xyz(1.0, 2.0, 3.0) # Set x to 1.0, y to 2.0 and z to 3.0

```

When using methods that take object arguments (and not raw X, Y and Z values), Soya automatically performs coordinate system conversion if needed. To move a `CoordSyst` at the same position than another one, use the `move` method:

```

coord_syst.move(coord_syst2)

```

Translation can be done by the `add_vector` method (which is aliased to the `+=` operator). The vector constructor accepts the parent (any `CoordSyst`), and then the X, Y and Z coordinates. For example, to move `coord_syst` one step on its right:

```

coord_syst.add_vector(soya.Vector(coord_syst, 1.0, 0.0, 0.0))

```

And to move `coord_syst` one step on the scene's right:

```

coord_syst.add_vector(soya.Vector(scene, 1.0, 0.0, 0.0))

```

Finally, `add_mul_vector(proportion, vector)` is a faster equivalent to `add_vector(proportion * vector)`, which is often used in `advance_time`.

2.6.3 Rotating

`rotate_x(angle)` (aliased to `rotate_vertical`), `rotate_y(angle)` (aliased to `rotate_lateral`) and `rotate_z(angle)` (aliased to `rotate_incline`) perform rotation around the `CoordSyst`'s **parent** X, Y and Z axes. The `turn_*` methods (`turn_x`, `turn_lateral`,...) are identical but they refer to the `CoordSyst` **local** X, Y and Z axes, and not its parent ones. All angles are in degrees.

```
coord_syst.rotate_y(90.0)
```

`rotate_axis(angle, axis)` performs a rotation around an axis defined by the origin (0, 0, 0) and the `Vector` axis.

```
coord_syst.rotate_axis(90.0, soya.Vector(scene, 0.0, 1.0, 0.0))
```

`rotate(angle, a, b)` performs a rotation around an axis that pass through a and b (either `CoordSysts` or `Points`).

```
coord_syst.rotate(90.0, scene, soya.Point(scene, 0.0, 1.0, 0.0))
```

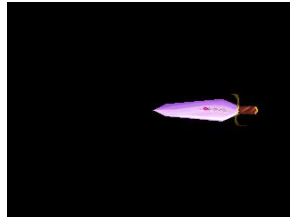
Finally, the very handy `look_at(direction)` method rotates a `CoordSyst` so as it looks toward direction (either a `Vector`, a `Point` or a `CoordSyst`); the -Z direction is considered as “front”, and `look_at` tries to maintain the Y direction as up (which is usually what one expects):

```
arrow.look_at(enemy)
```

2.6.4 Scaling

To scale a `CoordSyst`, use the `scale` method, which accepts three arguments, the X, Y and Z scale factors. Negative values can be used for mirroring.

```
coord_syst.scale(0.5, 0.5, 0.5)
```



The `scale_x`, `scale_y` and `scale_z` attributes are the current X, Y and Z scale factors (*e.g.* 0.5 in the previous example).

2.7 Time management and the MainLoop

In Soya, the time is divided in *round*, each round having the same theoretical duration (by default, 30 milliseconds). “Theoretical duration” means that a given round may be shorter or longer, but the mean duration is constant. The following three methods of `CoordSysts` are automatically called as time goes on (see figure 2.2):

`begin_round()` is called at the beginning of each round, for each `CoordSyst`. `begin_round` may *e.g.* perform collision detection, read events, determine the `CoordSyst` next move, and compute a speed vector.

`advance_time(proportion)` is called in proportion as time goes on; the proportion argument is the proportion of the round that has passed (1.0 for a complete round, 0.5 for half a round,... during a round, the sum of the proportion arguments in the different calls to `advance_time`, is always 1.0). `advance_time` is in charge of *e.g.* applying the speed vector computed by `begin_round`.

`end_round()` is called at the end of the round. It is rarely used.

The 3D rendering may occurs at any instant, possibly in the middle of a round, as if it was simultaneous (although Soya uses a single thread). This time managing system yields a very smooth and soft animation: *e.g.* if two third of a round has passed, two third of the movement will be done when the rendering occurs.

`MainLoop` is responsible for cutting the time as exposed above, and it does a good job. The `MainLoop` object constructor accpets one (or more) `World` arguments, which are the root scenes. Then the `MainLoop` is started by calling `MainLoop.main_loop`, and it loops until you call `MainLoop.stop(arg)`; `arg` will be the value returned by `MainLoop.main_loop` (see section 2.13.1 for more details on `MainLoop`).

For example, here is a subclass of `Body` that rotates continuously over the Y axis (see tutorial basic-2.py):

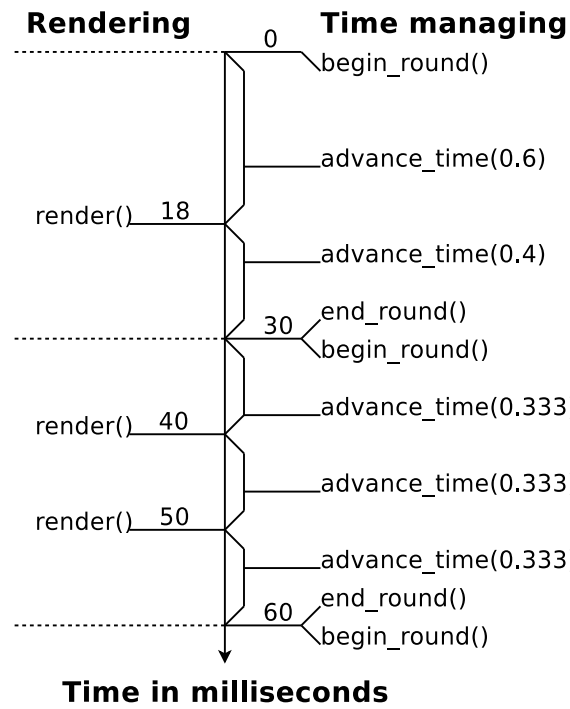


Figure 2.2: Time division in Soya

```
class RotatingBody(soya.Body):
    def advance_time(self, proportion):
        soya.Body.advance_time(self, proportion)

        self.rotate_y(proportion * 5.0)
```



As the rotation is always the same, we don't need a `begin_round`. The `advance_time` method calls the super implementation, and then rotates the object. Notice how the rotation angle takes into account the `proportion` argument (*e.g.* if half of the round has passed, half of the rotation is performed).

A more complex example is a randomly moving Body (see tutorial `basic-3.py`):

```
class RandomlyMovingBody(soya.Body):
    def __init__(self, parent = None, model = None):
        soya.Body.__init__(self, parent, model)
        self.rotation_speed = 0.0
        self.speed = soya.Vector(self, 0.0, 0.0, -0.2)

    def begin_round(self):
        soya.Body.begin_round(self)
        self.rotation_speed = random.uniform(-25.0, 25.0)

    def advance_time(self, proportion):
        soya.Body.advance_time(self, proportion)
        self.rotate_y(proportion * self.rotation_speed)
        self.add_mul_vector(proportion, self.speed)
```



This RandomlyMovingBody has two additional attributes: the rotation speed (in degrees, around the Y axis), and the speed vector. The speed vector is expressed in the RandomlyMovingBody coordinate system itself (remind that the -Z direction is the front).

begin_round computes a new random rotation speed (from -25.0 to 25.0); the speed vector doesn't need update since it is expressed in the RandomlyMovingBody coordinate system (*i.e.* rotating or moving the RandomlyMovingBody will rotate or move the vector). advance_time applies the rotation and speed vector; self.add_mul_vector(propotion, self.speed) is equivalent to self.add_vector(propotion * self.speed), but faster.

2.8 Grouping objects in Worlds

A World is a Body that can also have children CoordSysts nested in it (including other Worlds). When the World is moved, rotated or scaled, all the children CoordSysts are moved, rotated or scaled. For example, we can use nested World for representing celestial objects like suns/stars, planets and satellites. In this example, CelestialObject inherits from World, and continuously rotates (similarly to the RotatingBody example we've seen previously), but it can also contain other CoordSyst. As the CelestialObject rotates, the CoordSysts it contains are moved too.

For three CelestialObjects, the sun, the earth and the moon, the scene tree is:

```
World scene
|
+-- CelestialObject sun, displaying the sun Model
|   |
|   +-- CelestialObject earth, displaying the earth Model
|       |
|       +-- CelestialObject moon, displaying the moon Model
|
+-- Light light
|
+-- Camera camera
```

And here is the code (see tutorial nested-worlds-1.py):

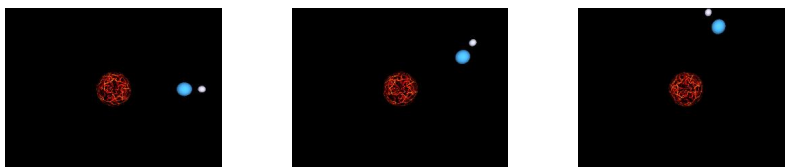
```
class CelestialObject(soya.World):
    def advance_time(self, proportion):
        soya.World.advance_time(self, proportion)
        self.rotate_y(proportion * 2.0)

sun = CelestialObject(scene, soya.Model.get("sun"))

earth = CelestialObject(sun, soya.Model.get("earth"))
earth.x = 2.0

moon = CelestialObject(earth, soya.Model.get("moon"))
moon.x = 0.5

camera = soya.Camera(scene)
camera.y = 4.0
camera.look_at(soya.Vector(scene, 0.0, -1.0, 0.0)) # Looks downward
soya.set_root_widget(camera)
```



Notice that the moon position ($X = 0.5$) is relative to its parent coordinate system (the earth), and not to the scene.

The easiest way to add a CoordSyst into a World is to pass the World as the first argument to the CoordSyst's constructor (as done previously):

```
earth = CelestialObject(sun, soya.Model.get("earth"))
```

However, it is also possible to use the add method:

```
earth = CelestialObject(None, soya.Model.get("earth"))
sun.add(earth)
```

Then, CoordSysts can be removed by the remove method:

```
sun.remove(earth)
```

The CoordSyst.parent attribute is the World currently containing the CoordSyst; this attribute is read-only (use remove and add to reparent a CoordSyst):

```
if moon.parent is earth: print "it's OK"
```

The World.children attribute is a list containing all the children CoordSysts (you **should not modify this list** directly, use add and remove!).

```
print earth in sun.children # => true
print moon in sun.children # => false
```

Worlds can also be iterated as list:

```
for coord_syst in sun:
    print "the sun contains", coord_syst
```

Soya also provide handy recursive methods. World.recursive() returns all the nested CoordSysts, recursively, and CoordSyst.is_inside(World) can be used to check recursively for inclusion:

```
print earth.is_inside(sun) # => true
print moon.is_inside(sun) # => true
```

World also has various methods for searching children, using predicate or the CoordSyst.name attribute. For example, to search (recursively) the scene for all Bodies that display the moon Model:

```
scene.search_all(lambda coord_syst: isinstance(coord_syst, soya.Body)
                and coord_syst.model is soya.Model.get("moon"))
```

Finally, Worlds can be turned into Model using the to_model() method. Models are faster than Worlds, but they are immutable (this will be discussed in detail in chapter 10).

2.9 Math computation: Point

As stated above, Soya defines a 3D position by three X, Y, Z values **and** the CoordSyst in which they are expressed. Soya provides Point objects for encapsulating the X, Y, Z coordinates and the CoordSyst. Using Points, Soya automatically converts the X, Y, Z coordinates from a CoordSyst to another when needed.

A Point represent a 3D position. To create a Point, use the constructor:

```
soya.Point(CoordSyst, x, y, z) -> Point
```

For example, this creates the Point located at X=1.0, Y=0.0, Z=0.0 in the earth (using the solar system example previously seen).

```
soya.Point(earth, 1.0, 0.0, 0.0)
```

The constructors are very similar to the CoordSyst's (and subclasses') ones, the first argument being the parent object. However, Point can be created in any CoordSyst, and not only World, and they are not considered as "3D objects". For example, they are not listed in World.children:

```
world = soya.World()
point = soya.Point(world, 1.0, 0.0, 0.0)
print world.children # => [] (empty list)
```

The distance between two CoordSysts or Points can be computed by the distance_to method:

```
print moon.distance_to(sun) # Notice that moon and sun are not defined in the same CoordSyst
```

Point provides the same moving methods than CoordSyst (see 2.6.2).

The parent attribute of a Point can be used to get or set the CoordSyst in which the X, Y, Z values are defined. If parent is set, X, Y, Z are left unmodified; if you want to perform a manual coordinate system conversion, use the convert_to method:

```

moon_center = soya.Point(moon, 0.0, 0.0, 0.0)
moon_center.convert_to(sun)
print "In the sun coordinate system, the center of the moon is", moon_center
# => In the sun coordinate system, the center of the moon is <Point 1.98, 0.0, 0.5
#     in <CelestialObject, model=<SimpleModel sun>>>

```

The % operator performs a similar conversion, but not in place (*i.e.* without modifying the object) : `obj % coord_syst` means `obj` expressed in the `coord_syst` coordinate system, *i.e.* either `obj` itself if `obj.parent` is already `coord_syst`, or a newly created `Point`. The following is thus equivalent to the previous example:

```

print "In the sun coordinate system, the center of the moon is", moon % sun

```

2.10 Math computation: Vector

A Vector represent a 3D vector; it can be used for translation or angular computation.

Hint: Vector inherits from Point, only to avoid duplicating some internal code, although this inheritance relation is mathematically absurd ;-).

To create a Vector, you can use either the constructor, or the `vector_to` method, which create a vector from a beginning position and an end position (both being `CoordSyst` or `Point`):

```

soya.Vector(CoordSyst, x, y, z) -> Vector
CoordSyst_or_Point.vector_to(CoordSyst_or_Point) -> Vector # Aliased to the >> operator

```

For example, to move character one unit forward, we first create the speed vector, which is `Z=-1` in the character `CoordSyst` (`-Z` being the front direction in Soya convention), and then we use `add_vector`:

```

speed = soya.Vector(character, 0.0, 0.0, -1.0)
character.add_vector(speed)

```

Like `Point`, `Vector` are not considered as “3D objects” and, in particular, they are not listed in `World.children`. `Vector` provides the same moving methods than `CoordSyst` (see 2.6.2).

The `length` method returns the length of the `Vector`; you can use the `set_length(new_length)` method to scale the `Vector` to the given length. The following example moves the moon 1.0 unit toward the sun (remind that `add_vector` perform a translation):

```

vector = moon.vector_to(sun)
vector.set_length(1.0)
moon.add_vector(vector)

```

`Vector` provides also some methods for dealing with rotations and angles. The `angle_to` method returns the angle between two `Vectors`; the following example computes the angle between the sun and the moon, at the earth position:

```

print (earth >> sun).angle_to(earth >> moon) # >> is the same than vector_to

```

For `Vector`, `add_vector` performs a vectorial addition (since translating a vector doesn’t change it and is thus useless). The `dot_product` and `cross_product` methods compute what you can expect from them.

Hints: Creating many `Points` or `Vectors` is time-consuming, since they are Python object. You can increase the performance by re-using the same objects instead of creating new ones.

2.11 The eye: Camera

2.12 Enlight your scene: Light

In Soya, colors are always four-value tuples of the form (red, green, blue, alpha). Each component ranges from 0.0 to 1.0. The alpha component is the transparency (0.0 means fully transparent, 1.0 means fully opaque). The alpha component is always mandatory, even if it is not used (*e.g.* for `Light` colors).

2.13 Basic object reference

2.13.1 MainLoop

MainLoop is in charge of managing and regulating time (see section 2.7). The current running MainLoop can be accessed as `soya.MAIN_LOOP`.

Constructor:

MainLoop(scene1, scene2,...) -> MainLoop

Noticeable attributes are:

fps the frame rate (number of frame per second, a usefull speed indicator; read only).

running true if the MainLoop is running (read only).

next_round_tasks a list of callable (taking no arg) that will be called once, just after the beginning of the next round. You can add callable if you want.

scenes the Worlds associated to the MainLoop. These Worlds `begin_round`, `advance_time` and `end_round` will be called regularly (as well as the ones of all objects inside the Worlds, of course).

round_duration the duration of a round, in second. Round is the time unit. It is granted that **all** rounds correspond to a period lasting `round_durection` (though the different period may not be regularly spread over time). (default to 0.030, *i.e.* 30 milliseconds).

min_frame_duration: minimum duration for a frame. This attribute can be used to limit the maximum FPS to save CPU time; *e.g.* having FPS higher than 30-40 is usually useless. Default is 0.020, which limits FPS to 40 in theory and to about 33 in practice (I don't know why there is a difference between theory and practice !).

Noticeable methods are:

main_loop() -> return_value starts the MainLoop. This method returns only after `MainLoop.stop` is called, and it returns the argument given to `MainLoop.stop`.

stop(return_value=None) stops the main loop. The stop doesn't occur immediately, but at the end of the next iteration. `MainLoop.stop` causes `MainLoop.main_loop` to returns; `return_value` is the (optionnal) value that `MainLoop.main_loop` will return.

reset() reter the internal time counter. You need to call `MainLoop.reset` if your program has paused, and you don't want the MainLoop to compensate the time loss by accelerating. This is usually the case when you put a game in pause mode.

update() calling regularly `MainLoop.update` is an alternative to `MainLoop.start` (see section 13.1).

begin_round()

advance_time(proportion)

end_round() default implementation calls all the corresponding methods of all scenes in the MainLoop.

render() called when it is time to render; default implementation calls `soya.render` that does the job.

2.13.2 Model

Model is a 3D model (sometimes called "Mesh" in other 3D engines). Model is actually an "abstract" class, and Soya provides several Model classes (`SimpleModel`, `AnimatedModel`,...). Models are created either by exporting them from 3D modelers (see chapter 5) or by creating a World, putting Faces in the World and then "compiling" the World into a Model (see chapter 10). Models are considered as immutable, as a single model can be shared and used by several Body; if you want to modify a Model in your code, you'll have to modify the World that has generated it, and then to turn the World into a new Model.

Models are not created by calling the Model constructor directly, they are loaded from a file or created from a World, respectively:

Model.get("filename") -> Model (see section 3)

World.to_model() -> Model

Noticeable attributes are:

filename the name of the file the model was loaded from (without path or extension).

materials a tuples of the materials the model uses.

2.13.3 CoordSyst

CoordSyst is the base class for all 3D objects. It defines a coordinate system, *i.e.* it has a 3D position, orientation and size. Constructor is:

CoordSyst(parent=None) -> CoordSyst where parent is the World in which the CoordSyst will be added (use None for no addition).

Noticeable attributes are:

parent the World that contains this CoordSyst (None if no such parent; read-only, use World.remove and World.add to reparent a CoordSyst).

x, y, z the X, Y and Z coordinates (defaults to 0.0, 0.0, 0.0).

scale_x, scale_y, scale_z the X, Y and Z scaling factors.

visible if false, the object is not displayed (defaults to true).

solid if false, the object is not taken into account for collision and raypicking (see section 8, defaults to true).

static if true, the object is considered as static (doesn't move), and Soya take that into account for optimizing rendering (default to false, may be modified automatically due to auto_static, see below).

auto_static if true, Soya automatically determines and sets the static attribute (defaults to true).

matrix, root_matrix, inverted_root_matrix the underlying 4x4 matrix, the root matrix (*i.e.* the multiplication of all matrices from scene.matrix up to CoordSyst.matrix), and the inverse of the root matrix (for debugging or hacking purpose only).

left_handed true if the CoordSyst is left_handed (read only, for debugging or hacking purpose only).

Noticeable methods are:

get_root() -> World get the root parent of the CoordSyst (the scene).

is_inside(coord_syst) returns true if the CoordSyst is inside coord_syst, *i.e.* both CoordSysts are the same, or coord_syst is a World that (recursively) contains the CoordSyst.

position() -> Point creates a Point in the same parent and at the same place than the CoordSyst.

distance_to(position) -> float returns the distance between the CoordSyst and position (another CoordSyst or a Point).

vector_to(position) -> Vector creates a Vector that starts at the CoordSyst position, and ends at the given position (another CoordSyst or a Point; aliased to the >> operator).

set_identity() resets the CoordSyst position, orientation and scaling.

get_sphere() -> (Point, float) returns a sphere (defined by the center Point, and the radius) that includes all elements in the CoordSyst.

get_box() -> (Point, Point) returns a sphere (defined by two corners) that includes all elements in the CoordSyst.

interpolate(state1, state2, factor) moves, rotates and scales the CoordSyst by interpolating between the two CoordSystStates state1 and state2. factor indicates the weight of the two CoordSystStates (0.0 means state1, 1.0 state2, and 0.5 half-way). XXX details interpolation in an other chapter; this feature is not yet stable.

set_xyz(x, y, z) set the x, y and z attributes in a single call.

move(position) moves the CoordSyst at the same place than position (another CoordSyst or a Point).

add_vector(vector) translates the CoordSyst by the given Vector (aliased to the += operator) .

add_mul_vector(k, vector) translates the CoordSyst by k times the given Vector (equivalent to, but faster than, add_vector(k * vector)).

add_xyz(x, y, z) translates the CoordSyst by (x, y, z) (expressed in the CoordSyst's parent coordinate system).

shift(x, y, z) translates the CoordSyst by (x, y, z) (expressed in the CoordSyst coordinate system).

rotate_x(angle), rotate_vertical(angle) rotates around the CoordSyst's parent X axis (like of you rotate the head vertically).

rotate_y(angle), rotate_lateral(angle) rotates around the CoordSyst's parent Y axis (like of you rotate the head laterally).

rotate_z(angle), rotate_incline(angle) rotates around the CoordSyst's parent Z axis (like of you roll the head).

turn_x(angle), turn_vertical(angle) rotates around the CoordSyst local X axis.

turn_y(angle), turn_lateral(angle) rotates around the CoordSyst local Y axis.

turn_z(angle), turn_incline(angle) rotates around the CoordSyst local Z axis.

rotate(angle, a, b) rotates around the axis defined by the a and b position (CoordSysts or Points).

rotate_axis(angle, axis) rotates around the axis defined by the origin (0, 0, 0) and the Vector axis.

rotate_xyz(angle, a_x, a_y, a_z, b_x, b_y, b_z) rotates around the axis defined by (a_x, a_y, a_z) and (b_x, b_y, b_z).

rotate_axis_xyz(angle, axis_x, axis_y, axis_z) rotates around the axis defined by the origin (0, 0, 0) and the (axis_x, axis_y, axis_z) Vector.

look_at(target) rotates the CoordSyst so as his front (*i.e.* -Z) direction points toward the given target, and tries to maintain the Y direction as the up direction.

look_at_x(target) is similar to look_at, but makes the X direction looking at the target, instead of -Z.

look_at_y(target) is similar to look_at, but makes the Y direction looking at the target, instead of -Z.

scale(x, y, z) scales the CoordSyst by x, y and z.

set_scale_factors(scale_x, scale_y, scale_z) sets the scale_x, scale_y and scale_z attributes in a single call.

get_dimension() -> (float, float, float) returns the width, height and depth dimension of the CoordSyst.

set_dimension(width, height, depth) scales the CoordSyst so as its dimensions are the given width, height and depth.

CoordSyst1 % CoordSyst2 -> Point returns a Point at the same place than CoordSyst1, but in the CoordSyst2 coordinate system (the returned value may be CoordSyst1 itself if it is already in CoordSyst2, or a newly created Point).

2.13.4 Body

Inherits from: **CoordSyst**.

A Body displays a Model at a specific 3D position. Model cannot be displayed without “emBodying” them; it allows to display the same Model at several location (*e.g.* two identical houses in a town), by creating two Bodies with the same Model.

Constructor is:

Body(parent=None, model=None, opt=None) -> Body where parent and model are obvious, and opt is an optional argument passed to the model (for AnimatedModel, it can be a list of the mesh names to attach, see chapter 4).

Noticeable attributes are:

model the Model the Body displays.

deforms the list of Deform applied to the Body (default to an empty list; you should not modify the list directly, but use the add_deform and remove_deform methods; see section 9.7).

The following attribute is only available if the Body's Model is an AnimatedModel (see chapter 4):

attached_meshes the list of the attached meshes names (only with AnimatedModel, see chapter 4).

Noticeable methods are:

add_deform(deform) applies the given Deform to the Body (see section 9.7).

remove_deform(deform) removes the given Deform from the Body (see section 9.7).

The following methods are only available if the Body's Model is an AnimatedModel (see chapter 4):

attach(mesh_name1, mesh_name2,...) attaches the meshes of the given names.

detach(mesh_name1, mesh_name2,...) detaches the meshes of the given names.

is_attached(mesh_name) -> int returns true if the mesh named mesh_name is attached.

animate_blend_cycle(animation_name, weight=1.0, fade_in=0.2) plays the animation of the given name in cycle, with the given weight (usefull is several animations are cycled simultaneously, which is possible), and **fade_in** is the time (in second) needed to reach the full weight, in order to avoid a brutal transition. The animation will **not** start at its beginning, but at the current global animation time, which is shared by all cycles (use **animate_reset** if you want to start a cycle at its beginning).

animate_clear_cycle(animation_name, fade_out=0.2) stops cycling the animation of the given name; **fade_out** is the time (in second) needed to stop the animation.

animate_execute_action(animation_name, fade_in=0.2, fade_out=0.2) plays the animation of the given name once; **fade_in** and **fade_out** are the time (in second) needed to reach full weight, and to stop the animation, in order to avoid brutal transitions.

animate_reset() immediately stops **all** animations, and resets the cycle animation time, *i.e.* future animations played with **animate_blend_cycle** will restart from their beginning.

set_lod_level() set the current LOD level (only if the Cal3D model file support it).

2.13.5 World

Inherits from: **Body**, **SavedInAPath**.

Constructor and loading class methods are:

World(parent=None, model=None, opt=None) -> **World** equivalent to **Body**'s constructor.

World.load(filename) loads a **World** (see section 3.7.1).

World.get(filename) loads a **World**, using a cache of already loaded **Worlds** (see section 3.7.1).

Noticeable attributes are:

children the list of children **CoordSyst** directly nested in the **World**. Do not modify the list (use the add and remove methods).

filename the **World**'s filename (relative to the <data>/worlds/ directory; defaults to None).

atmosphere the **Atmosphere**, defining the **World** atmospheric properties like fog, sky or background color (defaults to None, see section 9.6).

model_builder the **ModelBuider**, *i.e.* the object responsible for turning the **World** into a **Model** (defaults to None; in this case, a default **ModelBuilder** is used, see chapter 10). **ModelBuider** can be used to add shadows, cell-shading,...

The following attributes are only available if the **World**'s **Model** is an **AnimatedModel** (see chapter 4):

attached_coordsystems the list of the **CoordSysts** attached to a bone, containing (**CoordSyst**, **bone_id**, **option_flags**) tuples (only with **AnimatedModel**, see chapter 4).

Noticeable methods are:

add(CoordSyst) adds the given **CoordSyst** inside the **World**.

insert(index, CoordSyst) is similar to add, but insert the **CoordSyst** at the given index in the children list.

remove(CoordSyst) removes the given **CoordSyst** from the **World**.

recursive() -> **list of CoordSysts** returns the recursive list of children **CoordSysts**, *i.e.* the children list, plus the children list of the nested **Worlds**, and so on.

search(predicate) -> **CoordSyst** searches (recursively) for a **CoordSyst** that satisfies the given predicate; predicate is callable that take a **CoordSyst** argument and that return true of false.

search_all(predicate) -> **list of CoordSysts** is like search, but returns the list of all **CoordSysts** that satisfy the predicate.

search_name(name) -> **CoordSyst** searches (recursively) for a **CoordSyst** whose name attribute is the given name (aliased to **World[name]**).

subitem(namepath) -> **CoordSyst** returns the **CoordSyst** denoted by namepath. namepath is one or more names separated by dots, *e.g.* "character.head.mouth".

to_model() -> **Model** turns the **World** into a **Model** (see chapter 10).

raypick(origin, direction, distance=-1.0, half_line=1, cull_face=1, p=None, v=None) -> (Point, Vector) performs a raypicking, and returns either a (impact_point, normal_at_the_impact) tuple, or None (see section 8.1).

raypick_b(origin, direction, distance=-1.0, half_line=1, cull_face=1) -> int performs a raypicking, and returns 1 if there is a collision, and 0 if there is not (see section 8.1).

RaypickContext(center, radius, RaypickContext=None, items = None) -> RaypickContext creates a Raypick-ingContext. Raypick-ingContext are used to perform several raypicking in the same region, faster than by calling raypick or raypick_b (see section 8.1).

The following methods are only available if the World's Model is an AnimatedModel (see chapter 4):

attach_to_bone(CoordSyst, bone_name) attaches the given CoordSyst (which is understood to be a direct child of the World) to the bone of the given name. When the bone is moved by the animation, the CoordSyst moves too.

detach_from_bone(CoordSyst) detaches the given CoordSyst from a bone.

2.13.6 Camera

Camera is the “eye” from which the 3D scene is viewed. It also acts as the “ear”, for 3D sound. It also inherits from Widget (see section 11).

Inherits from: **CoordSyst, Widget**.

Constructor is:

Camera(CoordSyst) -> Camera

Noticeable attributes are:

front the minimum distance at which 3D objects can be seen (defaults to 0.1; cannot be 0.0).

back the maximum distance at which 3D objects can be seen (defaults to 100.0). If the back / front ratio is too big, you loose precision in the depth buffer.

fov the field of vision (or FOV), in degrees. Default is 60.0.

left, top, width, height the viewport rectangle, in pixel. Use it if you want the Camera to render only on a part of the screen. It defaults to the whole screen.

partial if true, the Camera is considered to use only a part of the screen, and not the whole screen, in particular for clearing purpose. Clearing a partial Camera is slower, but it doesn't clear the whole screen (defaults to false).

ortho if true, the Camera uses orthogonal perspective; if false (default) it uses real perspective.

listen_sound true if the Camera is used as the “sound listener”. A single Camera can be used so at the same time (defaults to true, see section 7.4).

to_render the world that is rendered by the Camera. Default is None, which means the root scene (as returned by get_root()).

master the master Widget (see section 11.2).

Noticeable methods are:

set_viewport(left, top, width, height) sets left, top, width and height in a single call.

get_screen_width(), get_screen_height() -> int gets the width and the height of the rendering screen, in pixel.

coord2d_to_3d(x, y, z, reused_Point=None) -> Point converts 2D coordinates X and Y (in pixel, *e.g.* mouse position) into a Point. Z is the Point Z coordinates (in the Camera coordinate system) ; it should be negative and defaults to -1.0. reused_Point is an optionnal Point that is used to store the result, if you want to avoid the creation of a new Point object and prefer reuse an existant one (for speed purpose).

coord3d_to_2d(Point) -> (x, y) converts a Point (or a CoordSyst) into 2D screen coordinates X, Y (in pixel).

render_to_material(Material, what) renders the camera to a Material's texture. 'what' is one of GL_RGBA, GL_LUMINANCE, GL_ALPHA.

is_in_frustum(CoordSyst) -> int returns true if the given CoordSyst is inside the Camera's frustum.

2.13.7 Light

Inherits from: **CoordSyst**.

Constructor is:

Light(CoordSyst) -> Light

Noticeable attributes are:

constant the constant attenuation of the Light (defaults to 1.0). This attenuation factor is not influenced by the distance.

linear the linear attenuation of the Light (defaults to 0.0). This attenuation factor is proportional to the distance.

quadratic the quadratic attenuation of the Light (defaults to 0.0). This attenuation factor is proportional to the square distance.

ambient the ambient color of the Light (defaults to no ambient, *i.e.* black or (0.0, 0.0, 0.0, 1.0)). This part of the Light is not affected by the Light's orientation or attenuation.

diffuse the diffuse color of the Light (defaults to white, *i.e.* (1.0, 1.0, 1.0, 1.0)). This color is the "main color" of the Light.

specular the specular color of the Light (defaults to white, *i.e.* (1.0, 1.0, 1.0, 1.0)). This color is used for the bright part of the object.

directional if true, the Light is directional (*e.g.* a sun). If false (default), The position of a directional Light doesn't matter, and only the constant component of the attenuation is used.

angle if angle is < 180.0, the Light is a spotlight; angle being the angle of the spot (defaults to 180.0).

exponent modifies how a spotlight Light is spread over space.

top_level if true, the Light pass through Portal (see section ; defaults to false).

cast_shadow if true, the Light casts shadows on Model with shadow enabled (default is true).

shadow_color the color of the shadows casted by the Light (default is semi-transparent black, *i.e.* (0.0, 0.0, 0.0, 0.5)).

2.13.8 Point

Constructor is:

Point(CoordSyst, x, y, z) -> Point

Noticeable attributes are:

x, y, z the X, Y and Z coordinates (defaults to 0.0, 0.0, 0.0).

parent the CoordSyst in which the Point is defined.

Noticeable methods are:

get_root() -> World get the root parent of the Point (the scene).

position() -> Point creates a Point in the same parent and at the same place than the Point.

distance_to(position) -> float returns the distance between the Point and position (another CoordSyst or a Point).

vector_to(position) -> Vector creates a Vector that starts at the Point position, and ends at the given position (another CoordSyst or a Point; aliased to the >> operator).

set_xyz(x, y, z) set the x, y and z attributes in a single call.

move(position) moves the Point at the same place than position (another CoordSyst or a Point).

add_vector(vector) translates the Point by the given Vector (aliased to the += operator) .

add_mul_vector(k, vector) translates the Point by k times the given Vector (equivalent to, but faster than, add_vector(k * vector)).

add_xyz(x, y, z) translates the Point by (x, y, z) (expressed in the CoordSyst's parent coordinate system).

copy() -> Point returns a copy of the Point

clone(other) changes in place the Point so as it is a clone of other (a Point or a CoordSyst).

convert_to(CoordSyst) converts in place the Point to the CoordSyst coordinates system. The x, y and z coordinates are modified, and the Point's parent is set to the given CoordSyst.

Point % CoordSyst -> Point returns a Point at the same place than the Point, but in the CoordSyst coordinate system (the returned value may be the Point itself if it is already in the right CoordSyst, or a newly created Point).

Point + Vector, Point - Vector -> Point translates the Point by the Vector.

2.13.9 Vector

Vector inherits from Point for implementation and internal purpose, although it can be seen as a mathematical absurdity. Constructor is:

Vector(CoordSyst, x, y, z) -> Vector

CoordSyst_or_Point.vector_to(CoordSyst_or_Point) -> Vector (aliased to **>>**).

Noticeable methods are:

length() -> float returns the length of the Vector.

set_length(float) scales the Vector so as its length is the given value.

normalize() scales the Vector so as its length is 1.0.

dot_product(Vector) -> float returns the dot product of two Vectors.

cross_product(Vector, reused_Vector = None) -> Vector returns the cross product of two Vectors; if reused_Vector is given, the result will be written in it instead of creating a new Vector.

angle_to(Vector) -> float returns the angle between the two Vectors (in degrees).

set_start_end(start, end) changes the Vector in place so as it starts and ends at the given start and end (Point or CoordSyst).

Vector + Vector, Vector - Vector -> Vector vectorial addition.

float * Vector scales the Vector.

2.13.10 Interesting methods for overriding

When overriding a Soya method, **don't forget to call the super implementation!**

CoordSyst.begin_round() (see section 2.7).

CoordSyst.advance_time(proportion) (see section 2.7).

CoordSyst.end_round() (see section 2.7).

CoordSyst.added_into(newparent) is called whenever the CoordSyst is added into a new World, or removed from its current World (in this case, newparent is None).

CoordSyst.loaded() is called **after** the object was loaded from a file. Notice that, if you want to perform some hacking on file loading that involves **several** objects, overriding CoordSyst.loaded is safer than CoordSyst.__setstate__, since other objects may not be fully initialized when CoordSyst.__setstate__ is called.

World.add(coordsyst)

Chapter 3

Managing data

3.1 Data path

Soya stores each class of object in a separate subdirectory in `<data>`, the data path given at the initialization. `<data>` is expected to contains the following subdirectories:

`<data>/images` contains image files (PNG or JPEG; for JPEG you should use the `.jpeg` extension, and not `.jpg`).

`<data>/materials` contains Soya Materials.

`<data>/models` contains Soya Models.

`<data>/animated_models` contains Soya AnimatedModels (in Cal3D format, using a directory per AnimatedModel, see chapter 4).

`<data>/world` contains Soya Worlds. These Worlds can either be though as 3D scenes.

`<data>/blenders` contains Blender models (see chapter 5).

`<data>/sounds` contains sound files (WAV or OGG Vorbis, see chapter 7).

`<data>/fonts` contains Fonts (see section 11.1).

These objects are the objects Soya can load; all of them inherit from `SavedInAPath` (excepted for Blender model, which are not Soya objects, of course). Other Soya objects can be saved, but not directly. For example, you cannot save just a `Body` in a file, but you can include a `Body` inside a `World`, and then you can save the `World`.

Known bug: Currently, Camera cannot be saved in files.

3.2 File formats

All Soya-specific objects (Materials, non-animated Models, Worlds and their content) are saved through serialization. Soya currently supports two file formats: Pickle and Cerealizer. Pickle (actually `cPickle`) is integrated into Python, and can save any object you may create, however **Pickle is not secure** for networking game. Cerealizer (<http://home.gna.org/oomadness/en/cerealizer>) is secure, but it requires you to register manually the class that are safe to read from a file.

The default file formats is to save files with Pickle, and to load either Pickle or Cerealizer files (Soya can determine automatically the format of a file; if Cerealizer is not installed, loading Cerealizer file is of course disabled). However, you are encouraged to use Cerealizer for security purpose.

To set the file formats, use the following function:

`set_file_format(saving_format, loading_formats = None)` where `saving_format` is the format for saving files (either a function with a signature like `pickle.dumps`, or a module with a `dumps` function), and `loading_formats` is the format for loading files (either a function with a signature like `pickle.loads`, or a module with a `loads` function), or a list of formats. If `loading_formats` is `None`, the loading formats are left unmodified.

The actual default (which may change) is equivalent to:

```
import cPickle, Cerealizer
set_file_format(cPickle, [cerealizer, cPickle]) # if Cerealizer is available
set_file_format(cPickle, cPickle)               # if Cerealizer is not available
```

To use only Pickle (for compatibility with older apps):

```
set_file_format(cPickle, cPickle)
```

To use Cerealizer while still being able to read cPickle files:

```
set_file_format(cerealizer, [cerealizer, cPickle])
```

To use only Cerealizer – **this is the only configuration safe for networking**:

```
set_file_format(cerealizer, cerealizer)
```

If you use Cerealizer you have to declare which class is safe for saving / loading. Soya automatically register Soya's classes, but you have still to register your derived classes. This can be done as following:

```
class YourClass(soya.CoordSyst):
    ...
cerealizer.register(YourClass)
```

If your class inherits from SavedInAPath, usually World, and you want YourWorld.get to work properly, you should do:

```
class YourWorld(soya.World):
    ...
cerealizer.register(YourWorld, SavedInAPathHandler(YourWorld))
```

And, if you want your objects to be saved in the directory <data>/your_worlds/ instead of <data>/worlds/, do:

```
class YourWorld(soya.World):
    DIRNAME = "your_worlds"
    _alls = weakref.WeakValueDictionary()
    ...
```

3.3 Saving objects

In Soya, saving an object is done in two steps (see tutorial basic-savingfile-pickle-1 and basic-savingfile-cerealizer-1):

```
obj.filename = "your_object"
obj.save()
```

The object is saved in the corresponding subdirectory in the first data path (*i.e.* soya.path[0]), and the file is named <filename>.data (*e.g.* <data>/worlds/your_object.data). To save the object again, just call obj.save. Images, Sounds, Fonts and AnimatedModels cannot be saved; as Soya is not able to modify them, it would be a non-sense.

When saving a reference to a SavedInAPath object (*i.e.* an Image, a Material, a Model, an AnimatedModel, a World, a Sound or a Font), if the object has a filename, only the filename will be saved. If it has not, the object will be saved normally. In the following example, the data of the sword Model are not saved in the scene's file:

```
scene = soya.World()
body = soya.Body(scene, soya.Model.get("sword"))
scene.filename = "sword_scene"
scene.save()
```

When the scene will be loaded, the sword Model will be loaded by calling soya.Model.get("sword"). As a consequence, you'll have to distribute the sword Model along with the scene.

3.4 Loading objects

Objects can be loaded with one of these class methods:

SavedInAPath.load(filename) -> SavedInAPath

SavedInAPath.get(filename) -> SavedInAPath

The difference between load and get is that load always return a new object, whereas get return the same object when it is called several time with the same filename. Images, Models, Sounds and Fonts are immutable in Soya, and thus get is the preferred method for loading them. For example, to load the sword_scene saved above:

```
scene = soya.World.load("sword_scene")
```

See also tutorial basic-loadingfile-1.

3.4.1 Extended filenames

The @ character is used to indicate some optional parameters in a filename:

For Fonts, it can be used to indicate the horizontal and vertical Font size (the horizontal size follows the @, then an x, then the vertical size). It can be used to create several Font objects of various sizes from a single Font file. *E.g.* :

```
font = soya.Font.get("indigo.ttf@20x30")
```

For Models and Worlds, it can be used to generate several Worlds and Models from a single Blender file (see section 5.5).

3.5 Auto-exporters and automatic conversions

When loading data, Soya can automatically perform the following conversions:

- Image -> Material
- Blender model -> World
- World-> Model
- Blender model -> AnimatedModel

Concretely, it means that, if you load (with either load or get) a Material that doesn't exist, and if there is an Image with the same filename, Soya will create a new Material, using this Image as texture, and saved (for future use). If the Material already exists, but there is a more recently modified Image with the same filename, Soya will load the Material, and automatically update the texture.

Similarly, when loading a World, Soya searches for a Blender model with the same filename, and, if needed, will export it to Soya (Notice that this require Blender to be installed). When loading a Model, Soya searches for a World (and thus for a Blender model), and, if needed, will load the World and re-turn it to a Model (Models are generated from Worlds, see chapter 10). This feature is known as "Soya's auto-exporters".

Auto-exporters are really nice for development, however they can be annoying in the final version of an application, for example one doesn't expect a game to start blender for re-exporting the model (when installing the game, the timestamp of the various files may be changed, messing up the whole auto-exporters system). To prevent that, you can disable auto-exporters as following:

```
soya.AUTO_EXPORTERS_ENABLED = 0
```

A common trick consists in enabling auto-exportes only for Subversion / CVS sources:

```
APPDIR = os.path.dirname(sys.argv[0]) # os.path.dirname(__file__) for a Python module
soya.AUTO_EXPORTERS_ENABLED = os.path.exists(os.path.join(APPDIR, ".svn"))
```

3.6 Where can i obtain Models?

First, you can design model yourself, using a 3D modeler like Blender (see chapter 5), or within Python scripts (*e.g.* for geometrical model; see chapter 10). Free models are also available:

- Nekeme Prod., an association for Free Game (as in Free Speech) Jiba is a member of, maintains the Free Data Repository. The FDR is a database of free resources for games, including 3D models, images, musics, sounds,... It can be browsed at <http://fdr.nekeme.net/>.
- You can also re-use the model of an existing free game, such as Balazar Brother (http://home.gna.org/oomadness/en/balazar_brother/index.html).

3.7 Object reference

3.7.1 SavedInAPath

SavedInAPath is an abstract mix-in class, used by Image, Material, Model, AnimatedModel, World, Sound and Font.

Noticeable class attributes are:

DIRNAME the data subdirectory used for saving the instance of this class, *e.g.* "models" for Model.

Noticeable attributes are:

filename the object's filename (relative to the <data>/<class>/ directory); if the extension is .data, it is not present in the filename. If the object has a filename, when saving other Soya objects that refer to it, only the filename will be saved (this allow to share *e.g.* a Model between two World scenes). If the object has no filename, the object will be duplicated in any other file that refer to it.

Noticeable class methods are:

load(filename) -> **SavedInAPath** loads the object saved in the <data>/<class>/<filename> file. Depending of the object, it may perform automatic conversion.

get(filename) -> **SavedInAPath** is similar to load, but, if called several times with the same with the same filename, it returns the same (cached) object instead of loading it twice.

availables() -> **list of strings** returns the list of the filename of all the objects available in the <data>/<class>/ directory.

Noticeable methods are:

save(absolute_filename=None) saves the object in <data>/<class>/<filename>, or in absolute_filename if given. Some objects (namely, Images, Sounds, Fonts and AnimatedModel) cannot be saved by Soya, and can only be loaded.

loaded() called when the object is loaded from a file; you may override it.

Chapter 4

Animated models

4.1 Loading animated model

AnimatedModels are loaded as usual, excepted that the model is in the Cal3D format, and not the Soya one. Auto-exporter works as usual with Blender, and generates Cal3D model as required. For example to load the Cal3D model located in `<data>/animated_models/balazar/` (corresponding to `<data>/blender/balazar.blend`, if it exists¹):

```
sorcerer_model = soya.AnimatedModel.get("balazar")
```

4.2 Displaying the model

AnimatedModel can be attributed to Body or World as any other Models:

```
sorcerer = soya.Body(scene)
sorcerer.shape = sorcerer_shape
```

4.3 Attaching meshes

A Cal3D model can be composed of several meshes, that can be attached (i.e. displayed) or not. Non-attached meshes are not visible. The AnimatedModel.meshes attribute is a dict mapping mesh names to their numerical ID. By default, all meshes are attached, but you can detach or attach some of them, as following:

```
print "Available mesh names:", sorcerer_shape.meshes.keys()
sorcerer.detach("helmet")
sorcerer.attach("armor")
```

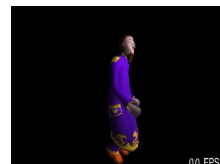
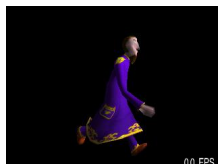
4.4 Playing animations

An AnimatedModel can have several animations ; the AnimatedModel.animations attribute is a dict mapping animation names to their numerical ID:

```
print "Available animation names:", sorcerer_shape.animations.keys()
```

To start playing an animation in loop, use the `animate_blend_cycle(animation_name, weight = 1.0, fade_in = 0.2)` method (see tutorial `character-animation-1.py`).

```
sorcerer.animate_blend_cycle("walk")
```



Notice that several animation can be played simultaneously, and blended together. The weight argument indicate the weight of the animation ; it defaults to 1.0 but may be changed if there are several simultaneous animations. The `fade_in` argument is the time (in second) to reach the full weight (in order to avoid a brutal transition, which corresponds to `fade_in = 0.0`).

Then, the animation can be stopped by the `animate_clear_cycle(animation_name, fade_out = 0.2)` method. The `fade_out` argument is the time (in second) required to fully stop the animation.

¹“Balazar” is just the name of my sorcerer!

```
sorcerer.animate_clear_cycle("walk")
```

Hint: When you start playing an animation with `animate_blend_cycle`, the animation may not start at the beginning, but at the current Cal3D internal counter value. The `animate_reset()` method can be used to reset this internal counter, so as cycled animations starts at their beginning.

```
sorcerer.animate_reset() # Ensure we start the walking animation at its beginning
sorcerer.animate_blend_cycle("walk")
```

Finally, a last method exists for animation: `animate_execute_action(animation_name, fade_in = 0.2, fade_out = 0.2)`. It plays an animation once, without the possibility to blend several animation at the same time. However, I use it rarely, since it is not possible to interrupt the animation before its end.

4.5 Attaching objects to bones

Soya allows you to attach Soya CoordSyst to the animated bones. This is extremely usefull if you want to add items to an animated character, like a sword. It can also be used for manual collision detection, since it allows to know where is located a part of the AnimatedModel. We are going to add a sword to the sorcerer. For that, we first need the sorcerer to be a World (instead of just a Body), and then we create a World corresponding to the right hand of the sorcerer. The right hand is added inside the sorcerer ; this is **mandatory** for attaching objects to bone !

```
sorcerer = soya.World(scene, sorcerer_shape)
right_hand = soya.World(sorcerer)
```

Now, using the `World.attach_to_bone(CoordSyst)` method, we attach the right hand to the sorcerer's bone named "right_hand" (this is the name given to the bone in Blender). This causes the righ hand World's position and orientation to be automatically updated according to the bone's position and orientation.

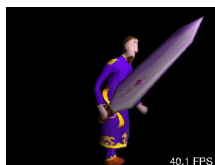
```
sorcerer.attach_to_bone(right_hand, "right_hand")
```

And finally, we create a sword Body in the right hand World :

```
sword = soya.Body(right_hand, soya.Model.get("sword"))
sword.rotate_z(180.0) # rotate and position the sword as needed
sword.set_xyz(0.05, 0.1, 0.0)
```

The resulting scene tree is the following (see tutorial character-animation-2.py):

```
World scene
|
+-- World sorcerer, displaying the Balazar AnimatedModel
|   |
|   +-- World right_hand, attached to the bone named "right_hand"
|       |
|       +-- Body sword, displaying the sword Model
|
+-- Light light
|
+-- Camera camera
```



You can detach a CoordSyst from a bone using the `World.detach_from_bone(CoordSyst)` method.

Hint: objects that are attached to bone must always be parented to the World that have the AnimatedModel, even if the bones are inserted one inside the other in Blender. For instance, you may have the following scene tree:

```
World scene
|
+-- World sorcerer, displaying the Balazar AnimatedModel
|   |
|   +-- World right_arm, attached to the bone named "right_arm"
|       |
|       +-- World right_hand, attached to the bone named "right_hand"
```

4.6 Object reference

4.6.1 AnimatedModel

Most of the attribute can be set in Python (*e.g.* `animated_model.sphere = (0.0, 0.0, 0.0, 2.0)`), in the .cfg Cal3D file (by adding *e.g.* `sphere=0.0 0.0 0.0 2.0`) or in the Blender file (by adding in a text buffer called 'soya_params' *e.g.* `sphere=0.0 0.0 0.0 2.0`, see section 5.4).

Noticeable attributes are:

animations a dictionary mapping animation names to their numerical ID.

meshes a dictionary mapping mesh names to their numerical ID.

materials a list of the Materials used by the AnimatedModel.

sphere a (x, y, z, radius) tuple defining a culling sphere for the animated model (a radius of -1.0 disable sphere culling, which is the default). You can set the sphere property for increasing performance.

double_sided if true, draw both sides of each face of the model. Default is true. It can be disabled for increasing performance.

shadow if true, the model casts shadows. Default is false.

cellshading if true, cell-shading is enabled. To enable cell-shading, use `set_cellshading()` or modify the Cal3D .cfg file or the Blender file.

Noticeable methods are:

set_cellshading(shader = DEFAULT_SHADER, outline_color = BLACK, outline_width = 4.0, outline_attenuation)
enable cellshading, with the given shader and outline properties. Set `outline_width` to 0.0 to disable outline.

Chapter 5

Blender for Soya

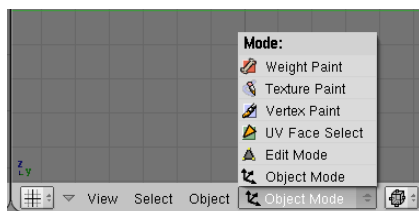
5.1 Modeling in Blender

The following Blender tutorial is very short and Soya-oriented. XXX add here some links to other Blender tutorials.

5.1.1 Drawing the mesh structure

The first step is to create the mesh structure in Blender. I usually start by adding a cube (Menu add->mesh->cube), and then I deform it, *e.g.* by selecting vertices (select them with the mouse right button) and then moving (press the “g” key), rotating (press “r”) or scaling (press “s”) them. You can also extrude (press “e”, or press space and then click the edit->extrude menu) some vertices or faces (to select a face, select all of its vertices).

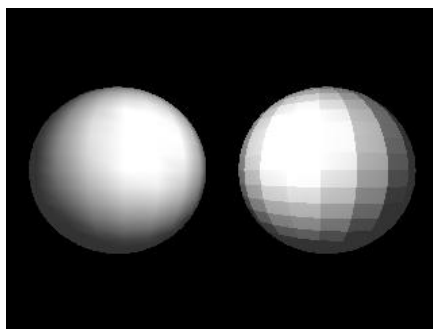
Blender has several modes; the first one is the object mode, and allows to move the different mesh objects you have (*e.g.* the cube). If you want to modify a mesh, select it (by clicking on it with the right mouse button) and change to the edit mode. A third mode, the face mode, will be used later for applying texture.



When drawing the mesh, you should use the Blender axis convention (X is right, Y is front and Z is up); the exporter automatically rotates the Model so as it uses Soya’s convention (X is right, Y is up and Z is back).

5.1.2 Smooth or solid lighting

Then you have to choose between smooth or solid lighting. Smooth lighting should be used for objects that are smooth by nature (although they are, as any 3D model, made of face). The following picture shows two spheres; the left one uses smooth lighting, and the right one uses solid lighting.



Notice that the smooth or solid lighting can be set on a per-face basis. In addition, Soya automatically remove the smooth lighting between two faces that make an angle higher than 80 degrees (this value can be changed by setting the `max_face_angle` parameter). This effect is not visible in Blender, but usually corresponds to what you expect.

5.1.3 Designing textures

Textures can be done in any 2D bitmap image editor, such as The Gimp. Textures should be PNG or JPEG images (with a .jpeg extension), and they should be saved in the `<data>/images/` directory. Soya support RGB and RGBA images, as well

as indexed colors. The **dimensions of the image must be powers of two** (e.g. 8, 16, 32, 64, 128, 256, 512,... pixels), but the image doesn't need to be a square.

Hint: Soya automatically check if the texture image has an alpha channel or not; however The Gimp (as well as other painting programs) sometimes automatically add an undesired alpha channel. Since alpha texture are slower than non-alpha one, and possibly buggy when two of them overlap (see “known bug” below), you should ensure it is not the case. If needed, remove the alpha channel (“flatten image ” in The Gimp).

Hint: In Blender, the length of the name given to a texture is limited to about 19 characters. As the exporter assume that this name is the name of the corresponding image file (which is the default value in Blender), you should avoid long filenames for textures.

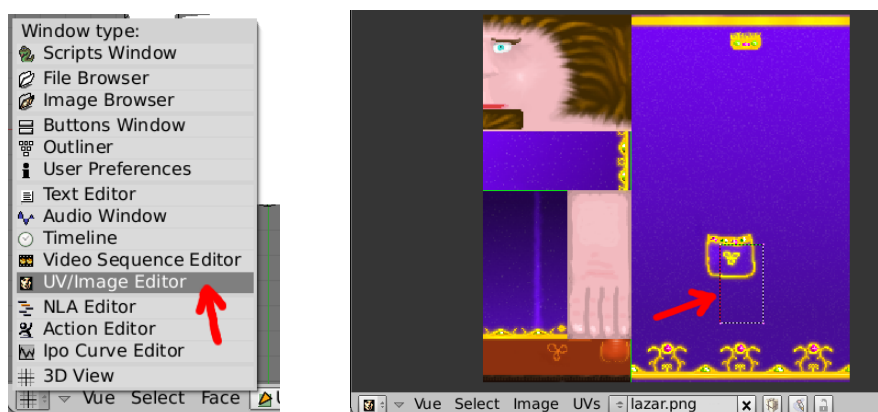
Known bug: When two semi-transparent objects overlap, because one of them is in front of the other, Soya may not render them well, i.e. the farther object in front of the other one. There are two possible workaround for this bug:

- For objects like a grid, an herbage or grass, use a texture with a “mask”, instead of a semi-transparent texture. A texture with a “mask” can have transparency, but not semi-transparency. Soya automatically uses a mask for texture with an alpha channel, with all alpha values being either 0.0 or 1.0 (255 in the Gimp integer notation).
- For special effects like spells or explosion, use additive blending (see section 10.1). In facts, which object is rendered first as no impact with additive blending, as a consequence the bug is now harmless. Moreover, additive blending often makes explosions or spells more impressive.

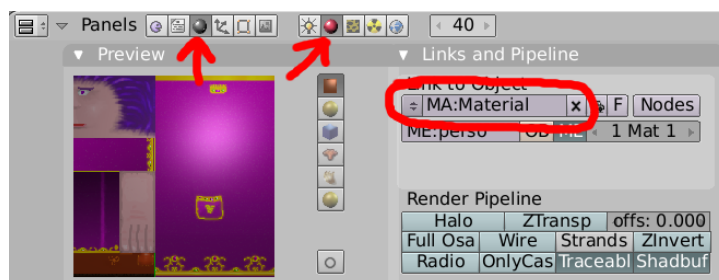
When an UV image is mapped to a face in Blender, Soya automatically exports it using the Material of the same name than the image filename, and creates this Material from the image if it doesn't exist yet.

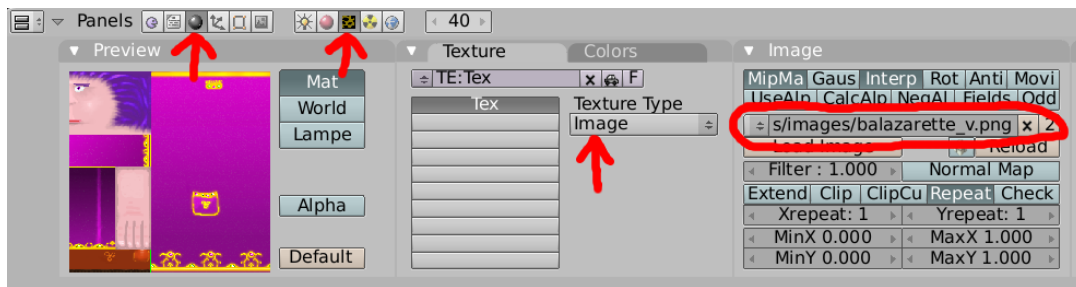
5.1.4 Applying the texture to the model

In Blender, enter in face mode, and select the faces you want to apply the texture to (press “a” to select all faces). Then go to the UV/Image editor window, and use the Image->Open menu to open your texture. Finally, position the UV coordinates by moving the vertex of the triangle or quad over the texture.



When exporting to AnimatedModel (i.e. to Cal3D format, using BlenderCal), each material need to be associated to the corresponding texture. This can be done by selecting the right material in the material panel (see the first screenshot below), and then by selecting in the texture panel, the “Image” texture type and the right image (see the second screenshot below).

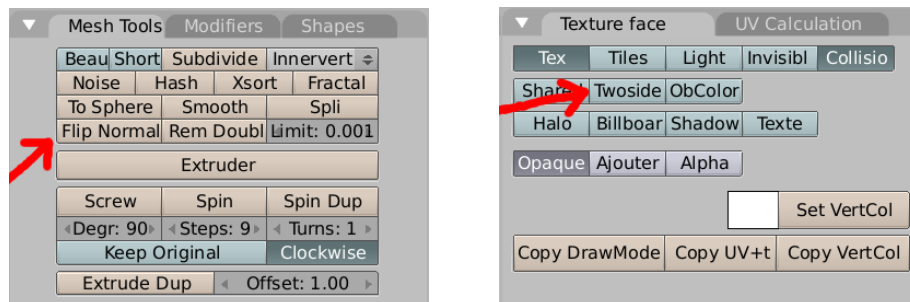




5.1.5 Face's sides

By default, Soya and Blender shows only one side of each face (Blender shows both side in some draw type modes, but not in the final rendering). Which side is visible depends on the normal of the face. If a face shows the wrong side, select it (by selecting all of its vertices in edition mode, or by selecting it in face mode, and then go to edition mode), and then click the “flip normal” button.

If you want to show both sides, select the face in face mode, and then click the “twoside” button.

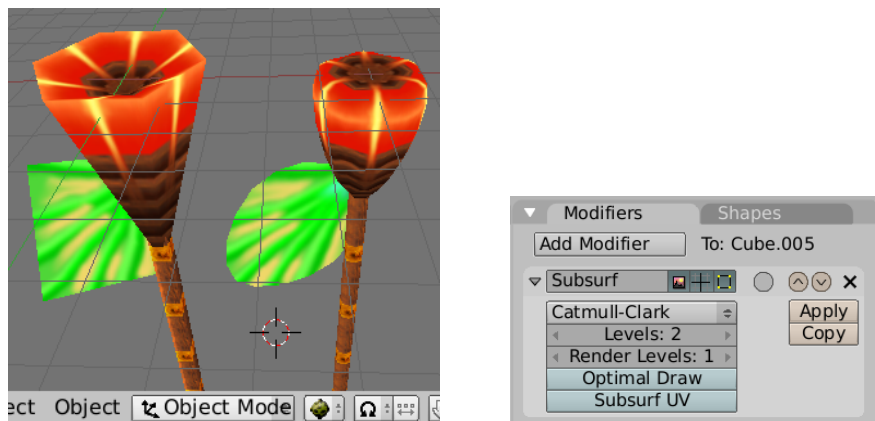


5.1.6 Adding face colors

You can also add per-face colors, although this feature is not commonly used. Soya exports them as per-vertex colors (since Soya doesn't support per-face colors).

5.1.7 SubSurf

In Blender, SubSurf can be used to automatically increase the details of a Model. The following picture show the same model without and with SubSurf:



When exporting non-animated Model, Soya automatically take SubSurf into account. However, this is not the case for AnimatedModel. A common trick is to apply the SubSurf on the Model (by clicking the “Apply” button); notice that applying SubSurf destroys any vertex group that you may have created, as a consequence it should be done **before** defining vertex groups.

5.1.8 Adding an armature

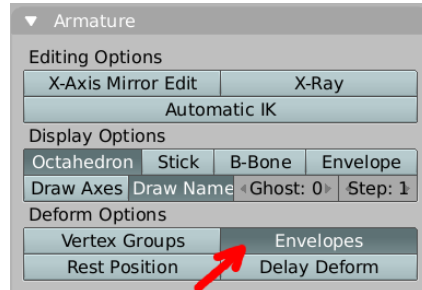
Blender's armatures are the skeletons used for animation. An armature is thus required only for AnimatedModel (although it may be used on non-animated Model, for generating several Soya Models being the same Blender model at different animation frame).

To add an armature, choose the Add->Armature menu, and then draw the armature's bones.

5.1.9 Linking bones to vertices

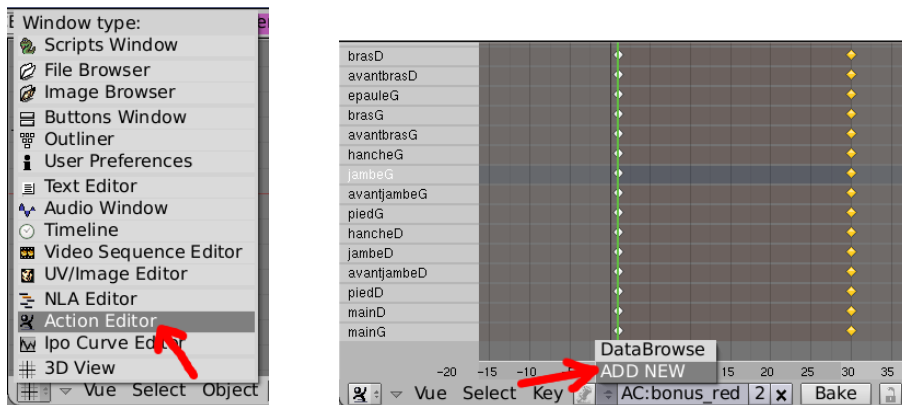
The second step for AnimatedModels is to link the armature's bones to the vertices. This can be done:

- Using vertex groups: select both the model and the armature (in that order), and click the Object->Parent->Make parent->Armature->Create from closest bones. Vertex groups corresponding to the various bones will be automatically created, and can then be refined manually. However, it seems that the recent version of Blender (2.41) are not as efficient for this than older version.
- Using envelopes: process as above, but choose “Don't create group” instead of “Create from closest bones”, and then check the “envelopes” button in the armature's properties.



5.1.10 Adding animations

In Blender, animations are called “actions”. Go to the “Action editor” window, add a new action, and give it a name. In the 3D window, select the armature and enter in the pose mode. Then move and rotate the bones, and add a keyframe with the Pose->Insert keyframe menu.



5.2 Auto-exporter

The easiest way to export Blender model is to use the auto-exporter (see section 3.5).

Simply save your Blender model in <data>/blender/ (e.g. <data>/blender/your_model.blend). Then in Soya, load the World or the Model of the same name (without extension), e.g.:

```
soya.Model.get("your_model")
soya.AnimatedModel.get("your_model")
```

Soya will automatically launch Blender, export the model, cache it in the <data>/worlds/, <data>/models/ and <data>/animated. directories, and quit Blender in a fraction of second.

If the Blender file is updated after that, Soya will automatically re-export it.

5.3 Blender features exported to Soya

Here is a summary of the following Blender features that are correctly exported to Soya:

Mesh structure

Face UV image (mapped to Face.material, see section 10).

Vertex UV texture coordinates (mapped to Vertex.tex_x and Vertex.tex_y, see section 10).

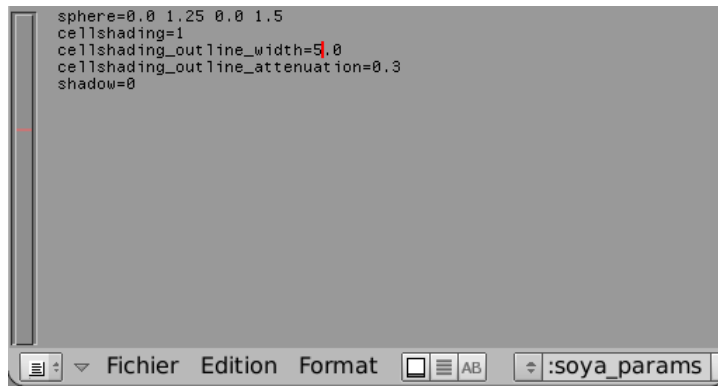


Figure 5.1: Using “parameter text buffer” in Blender

Face_twoside (mapped to Face.double_sided, see section 10).

Smooth or solid lighting (mapped to Face.smooth_lit, see section 10).

Face colors (mapped to Vertex.color, see section 10).

For non-animated Model only:

SubSurf

For AnimatedModel only:

Armature (also called “skeleton”).

Animation (called “action” in Blender).

AnimatedModel are exported to the Cal3D file format using BlenderCal (included in Soya source ; it requires Blender $\geq 2.42a$).

5.4 Adding Soya-specific attributes in Blender

Soya also provides some features that are not supported by Blender. These features can be defined using a “parameter text buffer” (see figure 5.1). First, create a text buffer in Blender, and name it “soya_params”. This text buffer contains Soya-specific informations, given as “key=value” pairs. The following pairs are supported:

scale=2.0 scales the Model (in the three directions).

shadow=1 activate shadows on the Soya Model (use 0 for disabling shadow, which is the default; see picture below).



cellshading=1 activate the cellshading on the Soya Model (use 0 for disabling cellshading, which is the default). A cellshaded Model use a different, more cartoon-like, lighting algorithm, and can have an outline (see the picture below; the sword on the left has not cellshading enabled, the sword on the right has it).

cellshading_shader=”filename” the name of the Material used as the “shader” (defaults to soya.SHADER_DEFAULT_MATERIAL). Only the texture of the Material is used; it should be a 1-pixel-wide alpha texture. This texture is then added over the normal Model texture, with the top-most pixels being added over the darker parts of the Model and the bottom-most pixels over the bright parts.

The `animation` and `animation_time` can be used to generate several non-animated Model corresponding to the various frames of one or more Blender actions. For example, to generate a non-animated Model that is a statue of Balazar running, at the frame 2:

```
animation=run
animation_time=2.0
```

5.6 Exporting Soya model to Blender

The script `soya/soya2blender.py` (in the Soya sources) can import a Soya Model in Blender. You have to modify the end of the script to choose the Model to import, and then run the script manually in Blender.

Known bug: It seems that `soya2blender.py` doesn't export texture well, so you'll have to re-set the texture.

5.7 What about other 3D modelers ?

In addition to Blender, the following modelers are supported by Soya:

- 3DSMax (see `soya/_3DS2soya.py`).
- MilkShake 3D (see `ms3D2soya.py`).
- OBJ/MTL (see `objmtl2soya.py`).

Chapter 6

Event handling

6.1 Getting events

XXX Soya's event system is still quite primitive and need a rewrite.

`soya.process_events()` computes and returns all events that have occurred since the last call to `process_events`.

An event is a tuple ; the first value of an event tuple is a constant from `soya.sdlconst`, and the following values depend of the event type. Event types are:

```
(sdlconst.KEYDOWN, key, mods[, unicode_key])
(sdlconst.KEYUP, key, mods[, unicode_key])
(sdlconst.MOUSEMOTION, x, y, x_relative, y_relative, state)
(sdlconst.MOUSEBUTTONDOWN, button, x, y)
(sdlconst.MOUSEBUTTONUP, button, x, y)
(sdlconst.JOYAXISMOTION, axis, value)
(sdlconst.JOYBUTTONDOWN, button)
(sdlconst.JOYBUTTONUP, button)
(sdlconst.VIDEORESIZE, width, height)
(sdlconst.VIDEOEXPOSE)
(sdlconst.QUIT)
```

`unicode_key` is present only if `soya.set_use_unicode(1)` has been called.

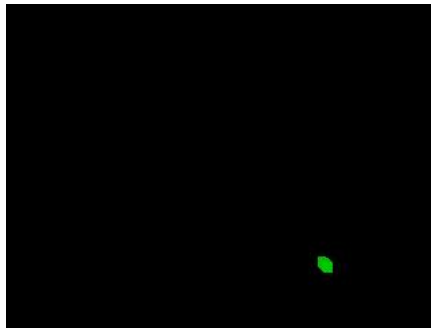
6.2 Converting mouse 2D coordinates to 3D coordinates

Mouse coordinates are returned as pixel values by `process_events()`. These 2D pixel values can be converted into 3D coordinates using `Camera.coord2d_to_3d(x, y, z = -1.0) -> Point`. As mouse coordinates are 2D, the Z value cannot be guessed; if not given, it default to -1.0. Remind that, if you want the mouse to be in front of the Camera, you need $z < 0.0$.

For example, you can use the following example to display a 3D cursor (see the `mouse-1` tuto, and the `raypicking-2` tuto for an example of drag-drop):

```
class Cursor(soya.Body):
    def __init__(self, parent, model = None):
        soya.Body.__init__(self, parent, model)

    def begin_round(self):
        soya.Body.begin_round(self)
        for event in soya.process_event():
            if event[0] == soya.sdlconst.MOUSEMOTION:
                self.mouse_pos = camera.coord2d_to_3d(event[1], event[2], -15.0)
                self.move(self.mouse_pos)
```



6.3 Converting 3D coordinates to 2D coordinates

3D coordinates can be converted to 2D pixel values using `Camera.coord3d_to_2d(position) -> (x, y)`, where position is either a `Point` or a `CoordSyst`.

Chapter 7

Sounds

Soya's sound API is very similar to the API for 3D objects.

7.1 Loading sounds

Soya support currently the following sound file formats:

- WAV (through the Python wave module)
- OGG Vorbis (requires the PyOgg and PyVorbis Python module)

Sound files should be placed in your `<data>/sounds` directory (see chapter 3). You can load a sound by doing:

```
sound = soya.Sound.get("my_sound.wav")
```

Soya uses a kind of streaming to not have to read the whole sound file before starting playing. The Sound object contains only the sound raw data.

7.2 Playing sounds: SoundPlayer

To play the Sound, you need to put it into a SoundPlayer, a subclass of CoordSyst that plays a Sound in a 3D environment (SoundPlayer is to Sound what Body is to Model):

```
sound_player = soya.SoundPlayer(parent, sound)
```

That's all! The Sound will be played at the position of the SoundPlayer, and Soya will automatically take care of the Doppler effect. Moving the SoundPlayer (or his parent, of course) will move the source of the Sound; see the `sound-1.py` tutorial for an example. When the Sound is over, by default Soya automatically removes the SoundPlayer from its parent. To stop playing the Sound before the end, just remove manually the SoundPlayer from its parent.

To play a background music in loop, at no particular 3D position:

```
sound_player = soya.SoundPlayer(parent, sound, loop = 1, play_in_3D = 0)
```

Hint: the `sound` and `play_in_3D` attributes are currently read-only (this may change in the future), and thus you'll have to set them when calling the constructor.

Hint: when a World containing a SoundPlayer is saved, Soya saves the current playing position. When the World will be loaded, the sound will restart **at (about) the same position**, and not at the beginning.

Hint: as WAV files are not seekable through the wave Python module, loading SoundPlayer that are playing WAV can be slow, particularly for big file. As a consequence, you should prefer the OGG Vorbis format for big files like music.

7.3 Sound initialization

`soya.init` accept the following optional sound-related parameters:

sound is true to initialize 3D sound support (default to false for backward compatibility).

sound_device is the OpenAL device names, the default value should be nice (default tries native, esd, sdl, alsa, arts, and null devices, in order).

sound_frequency is the sound frequency, in Hz (defaults to 44100).

sound_reference_distance is the reference distance for sound attenuation (defaults to 1.0). Increase this value if you find that sounds far from the camera are too much attenuated.

sound_doppler_factor can be used to increase or decrease the Doppler effect (defaults to 0.01, which sounds a nice value).

Additionally, the `set_sound_volume` function can be used to control the global sound volume, ranging from 0.0 (no sound) to 1.0 (default and maximum value):

```
soya.set_sound_volume(0.5)
```

Use `soya.get_sound_volume()` to get the current sound volume.

7.4 Sound and multiple Cameras

Soya uses the Camera as the “ear” from which sounds are listened. However, you can have only a single “ear” at the same time. If you have several Cameras, you have to choose the one that will act as the “ear”. This can be done through the `listen_sound` attribute of the Camera: if this attribute is false, the Camera doesn’t act as a “ear” (the default value is true):

```
camera.listen_sound = 0
```

7.5 Object reference

7.5.1 Sound

Inherits from: **SavedInAPath**.

Loading Sounds:

Sound.get(filename) -> Sound loads a Sound from the `<data>/sounds/` directory; filename should include the sound extension (*e.g.* `.wav` or `.ogg`).

Noticeable attributes are:

filename the sound’s filename (relative to the `<data>/sounds/` directory).

stereo is true if the sound is stereo, and false if the sound is mono.

7.5.2 SoundPlayer

Inherits from: **CoordSyst**.

Constructor is:

SoundPlayer(parent, sound, loop, play_in_3D, gain, auto_remove) -> SoundPlayer the parameters directly match the attributes.

Noticeable attributes are:

sound is the Sound to play (read-only).

loop if true, the sound restarts from the beginning when it ends (defaults to false).

play_in_3D if true, the sound is played as a 3D sound; if false, as a 2D sound (read-only; defaults to true). Notice that OpenAL cannot play stereo sound in 3D, and you’ll get an error if you try that.

gain is the volume of the Sound, ranging from 0.0 to 1.0 (default 1.0).

auto_remove if true, the SoundPlayer is automatically removed when the sound ends (excepted in cases of looping!, defaults to true)

Noticeable methods are:

ended() this method is called when the sound is over. You may override it; the default implementation removes the SoundPlayer from its parent if its `auto_remove` attribute is true.

Chapter 8

Collision detection and physics

8.1 Raypicking

8.2 Collision (ODE support)

8.3 Physic engine

8.4 Object reference

Chapter 9

Advanced Soya objects

9.1 Terrain

9.1.1 Basics

9.1.2 Generating your own terrain

9.2 Particle systems

9.3 Traveling camera

9.4 Sprites

9.5 Portal

9.6 Atmosphere

9.6.1 Basic Atmosphere

9.6.2 NoBackgroundAtmosphere

9.6.3 SkyAtmosphere

9.7 Deforming Models

9.8 Object reference

9.8.1 Terrain

9.8.2 ParticleSystem

9.8.3 TravelingCamera

9.8.4 Traveling

9.8.5 ThirdPersonTraveling

9.8.6 Sprite

9.8.7 Portal

9.8.8 Atmosphere

9.8.9 SkyAtmosphere

9.8.10 Deform

Chapter 10

Modeling

The Soya modelling system allows to create Soya model from Python code, without using Blender or any other 3D modeller. It is also used for writing exporters for 3D modellers.

Soya Model are created by putting several Faces (triangles or quads) in a World, and then converting the World into a Model

10.1 Materials

A material

10.2 Basic Models: cube and sphere

The `soya.cube` and `soya.sphere` module provide functions for creating cube and sphere. These functions simply call lower lower functions for creating cubic or pherical models.

10.3 Faces and vertices

In Soya, each model is made of Faces.

10.4 Modelifiers

10.5 Static lighting

10.6 Object reference

10.6.1 Image

10.6.2 Material

10.6.3 Vertex

10.6.4 Face

10.6.5 ModelBuilder

Chapter 11

Font, text, and widget systems

11.1 Fonts and text drawing

11.2 Widgets

11.3 Pudding

11.4 Object reference

11.4.1 Font

11.4.2 Label3D

Chapter 12

Tofu and Soya

12.1 Using the Tofu network engine

12.2 Object reference

Chapter 13

Using Soya with...

13.1 External GUI systems (Tk, Wx,...)

Many GUI systems provide their own main loop. In this case, you should create the Soya's MainLoop object as usual, but instead of calling `MainLoop.main_loop()`, you should call `MainLoop.update()` repeatedly, usually in a kind of timer, if possible about once per 25 or 30 milliseconds. `MainLoop.update` manages time similarly than `MainLoop.main_loop`, but it cannot regulate time, as a consequence, you should use `MainLoop.main_loop` whenever possible.

13.1.1 Tkinter

Using Tkinter, this can be done as following, with `after`:

```
class Window(Tkinter.Tk):
    def __init__(self):
        Tkinter.Tk.__init__(self)
        self.after(30, self.update_soya)

    def update_soya(self):
        self.after(30, self.update_soya)
        soya.MAIN_LOOP.update()
```

See tutorial `soya-with-tk-1.py` for an example.

13.2 PyGame

Using Soya on PyGame surface is possible, by initializing first the PyGame surface, and then initializing Soya as following:

```
soya.init(create_surface = 0)
```

However, this is of little interest, since PyGame doesn't seem to be able to blit on OpenGL surface.

Chapter 14

Extending Soya in Python

- 14.1 Direct calls to OpenGL
- 14.2 Writing new Materials
- 14.3 Writing new CoordSysts
- 14.4 Object reference

Chapter 15

Hacking the Soya sources

The source of the development version of Soya can be found on our Subversion repository: <http://gna.org/svn/?group=soya>. Soya is written in Pyrex, Python and there is still a small part in C.

You can propose patches on the Soya mailing list. However, I (=Jiba, the Soya maintainer) am a very occupied guy with a small memory :-). If you don't get any feedback after while, it probably doesn't mean your proposition has been rejected, but rather that no one got the time for looking at it, and it has been forgotten... in this case just insist!

Do not hesitate to ask for Subversion write access, too.

Hint: Compiling Soya takes quite a long time. However, you can speed up the compilation by disabling GCC's optimization, as following:

```
export CFLAGS=-O0
```

15.1 Dealing with Segfaults

Sometimes, Soya may crash and cause segmentation faults. It corresponds to error occurring at the Pyrex level. In this case, do as following to obtain a backtrace :

```
gdb python
run ./your_soya_script.py
[wait until the script crashes]
bt
[the backtrace is here]
```